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A0104 Position mode lagless, encoder 1

The drive is in position control. The position control loop is closed in the drive via a position encoder. The master only presets the position command value characteristic, the drive follows the command value without a lag distance [prerequisite: "Velocity feedforward: Gain" (0x2224:01 / P-0-0040 / --) has been set to 100%].

"Encoder 1" means that the encoder assigned via "Encoder interface assignment ENC_1: Value" (0x2480:01 / P-0-0077 / --) is used as the control encoder.

See also "Position control" (Sercos) or "Cyclic sync position mode" (CoE)

▶ Attributes